

CERES Clouds Working Group Report

CERES

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- Data processing status
- Ed5 cloud algorithm development and evaluation
 - Consistency of cloud properties across satellites
 - Neural Net for cloud top heights
 - Two-habit ice model in GEO
 - 2-channel satellite update
- New SatCORPS capabilities

NASA Clou	uds Processing Status (N	AODIS & VIIRS)
CERES-MODIS Edition 4 (*CDR)	Aqua: Jul 2002 – Feb 2023 (~ 20.5 y) Terra: Feb 2000 – Feb 2023 (~ 23 y)	 Uses frozen Ed4 cloud codes delivered in 2013 MODIS Collection 5 radiances thru Feb 2016, MODIS Collection 6.1 March 2016 – present and scaled to C5 for consistency over entire record Terra-MODIS normalized to Aqua-MODIS (Sun-Mack, et al. 2018)
CERES-VIIRS Edition 1A	SNPP: Jan 2012 – Jun 2021 (~ 9.5 y) NOAA-20: Jan 2018 – Jun 2021 (~ 3.5 y)	 Uses VIRS Ed1A cloud code SNPP uses forward processing calibrations (C1 radiances), not scaled to MODIS; has discontinuity ~2016 due to a calibration update by SIPS N20 uses C2 radiances and scaled to MODIS C5
CERES-VIIRS Edition 2A	SNPP: Jan 2012 – Feb 2023 (~ 10 y)	 Uses VIIRS Ed1A cloud code Uses C2 radiances and scaled to MODIS C5
CERES-VIIRS Edition 1B (*CDR)	NOAA-20: Jan 2018 – Feb 2023 (~ 5 y)	 Uses new version of VIIRS cloud code (temporary continuity version until Ed5 is released) Fills Aqua-MODIS gap in Aug 2020

S EARTH'S RADIAN



Ed5 Cloud Algorithms



- MODIS and VIIRS algorithms will be as similar as possible and use 11 common channels while retaining many of the advances made for Ed4.
- For GEO (20+ satellites), a 3-channel approach is developed and being evaluated for daytime (0.63, 3.9, 11 μ m) and nighttime (3.9, 11, 6.7 μ m).
 - except for Met-5, Met-7, and GMS-5 (0.63, 11 $\mu m)$ which comprise 20% of GEO data
- To improve accuracies and consistency, Ed5 LEO and GEO algorithms have bug fixes, refined cloud masks, updated cloud models & atmospheric corrections, use of new ancillary datasets (e.g. snow/ice maps, clear sky radiances), and incorporation of machine learning algorithms.
- Ed5 cloud algorithms will employ information from the GEOS-IT to keep pace with latest GMAO reanalysis systems
 - GEOS-IT datasets must be in place to finalize algorithms

MODIS Central	VIIRS Central
Wavelength	Wavelength
(µm)	(μm)
0.65	0.64
1.61	1.61
2.13	2.26
3.78	3.74
11.0	10.8
12.0	12.0
8.55	8.55
1.24	1.24
0.47	0.49
1.38	1.38
0.86	0.86
-6.71-	N/A
- 13.3 -	N/A



Ed5 Cloud Algorithm Evaluation (Initial versions)



Ed5 challenge: To what extent can we develop and apply common algorithms to disparate LEO and GEO data?

- Cross-platform consistency is a difficult given all of the satellite imagers in the record and their different characteristics.
- Our current focus is on MODIS/VIIRS consistency and the consistency across GEO sensors, particulary with respect to cloud detection (first order problem).
- Goal is to apply a similar cloud mask (10-channels) to MODIS/VIIRS and likewise a common 3-channel mask to the GEO's (want to avoid having to tune 23 GEO satellites).

Evaluations

- Cloud property comparisons between Aqua-MODIS and NOAA-20 VIIRS in Ed5 vs. Ed4/Ed1B which comprise the current cloud CDR.
- Cloud property comparisons between GOES-16 and GOES-13 to evaluate Ed5 consistency relative to Ed4.



- Focus on non-polar ocean (land mask, polar night awaiting new inputs)
- Untuned (left) is the same cloud mask (v1) applied to MODIS and VIIRS
- Good agreement in many oceanic areas except at low latitudes where many more high clouds are being detected from MODIS
- Tuned version (right) applies different cloud masks, e.g. Thin cirrus test: If T11-T12 > X, then test passes (cloud) X = 1.5 K (MODIS) & X = 2.2 (VIIRS), X is expected clear sky BTD
- Problems: Tuning is subjective, must tune all 25+ satellites (?),
 X is constant everywhere (can lead to whack amole)

Why tune (why does X vary)?





 In the latest version (v3), this thin cirrus test is modified so that the clear sky simulations are included in the threshold to better account for regional variations in water vapor absorption on T11 and T12.

T11-T12 > X + (csT11-csT12) , X is same for MODIS and VIIRS

• This produces monthly mean differences that are consistent with the tuning approach but allows us to apply an identical cloud mask to both sensors.

Why tune (why does X vary)?



Daytime Total Cloud Fraction Difference: VIIRS minus AQUA

Jan

2019

July 2019



- VIIRS Ed1B tuning to MODIS Ed4 results mixed
- Fewer oceanic clouds detected from VIIRS



- Ocean and polar land consistency better with Ed5 approach
- Non-polar land mask needs work, awaiting new inputs

July Daytime Cloud Fraction Difference by Phase: VIIRS minus AQUA



• Non-polar land mask needs work, awaiting new inputs

July 2019 Daytime COD and CER Differences: VIIRS minus AQUA

COD

CER

Ed5 v3









G:L=0.36(0.63) O=0.16(0.79) LO=0.21(0.75) P:L=0.01(0.55) O=-0.28(1.51) LO=-0.16(1.28) NP:L=0.41(0.63) O=0.19(0.45) LO=0.25(0.51)



Nighttime Total Cloud Fraction Difference: VIIRS minus AQUA





- Ed5 ocean consistency much better (VIIRS still a little low)
- New land mask and Nnet for polar night coming soon

July Nighttime Cloud Fraction Difference by Phase: VIIRS minus AQUA

lce



Poor agreement at low latitudes and southern ocean



Ed5 not much better

Cloud phase logic needs revisit

Ed5 Cloud Fraction Comparisons with CALIPSO Jan/July 2019



Daytime zonal means compare well with CALIPSO. Some seasonal dependencies for MODIS/VIIRS level of agreement (??)

Ed5 Cloud Fraction Comparisons with CALIPSO Jan/July 2019



MODIS/VIIRS generally consistent at night in zonal means but under-detecting some low clouds compared to CALIPSO



Higher Accuracy Cloud Top Heights using Neural Net

All clouds, daytime, snow/ice free













Higher Accuracy Cloud Top Heights using Neural Net All clouds, daytime, snow/ice free



All	Nnet	Ed4	
Bias	-0.01	-1.53	
MAE	1.07	2.24	
RMSE	1.77	3.55	

All Clouds

Low Clouds			
Low	Nnet	Ed4	
Bias	0.60	0.31	
MAE	0.85	0.89	
RMSE	1.64	2.01	

Mid Clouds

Mid	Nnet	Ed4
Bias	0.51	-0.80
MAE	1.14	1.63
RMSE	1.69	2.20

High Clouds

High	Nnet	Ed4
Bias	-0.48	-2.75
MAE	1.18	3.14
RMSE	1.86	4.38







- Two-habit ice scattering model for ice clouds implemented
- Use of GOES-13 and GOES-16 overlap period to evaluate consistency with a common cloud algorithm

GOES-13: 5-band 2nd generation imager, 4-km IR

GOES-16: 16-band 3rd generation imager, 2-km IR

• Clear sky Land/ocean reflectance update for 2-ch satellites



Daytime Cloud Fraction (SZA<75°)

Mean GOES-16 THM

THM – SHM

60

40

20

0

-20

-40

-60

40

20

0

-20

-40

-60 -120

-120

-100

-100





July 2017

100

90

80

70

60

50

40

30

20

10

7.5

4.5

1.5

-1.5

-3

-4.5

7.5

10

Some notable differences in cloud phase arise due to the change in ice models



Ice Cloud Optical Depth Comparison (ΔCF<1%)



Mean GOES-16 Tau (THM)



Mean GOES-16 R_e (THM)





THM – SHM R_e (Δ = -10.8 μ m)



July 2017, Day

Ice cloud Tau mostly decreases with THM as expected due to the lower asymmetry parameter at 0.65 μm

Ice cloud R_e decreases substantially for THM due to larger asymmetry parameter for THM at 3.9 µm

GEO results consistent with MODIS





GOES-16 vs GOES-13 3-channel code with THM

Overlapping period with equivalent subsatellite point (Dec 14-31 20217)

GOES-16 data spatially averaged to match GOES-13 resolution

Hourly observations, 15-minutes apart



Daytime Total Cloud Fraction (SZA<75°)



Mean GOES-16 (3ch)



G16 – G13 (Ed4)



G16 - G13 (Ed5)





Daytime Cloud Fraction by Phase (SZA<75°)



10

-100

-80

-60

-40

-120

Mean GOES-16 (3ch) G16 – G13 (Ed4) G16 – G13 (Ed5) Daytime liq CF (G16) 3ch THM, Mean=48.45% Δ Day Liq CF (G16-G13), Mean Δ=-1.05% Δ Day Liq CF (G16-G13), Mean Δ =-1.09% 100 60 60 70 20 20 60 50 40 -20 -20 30 20 -10 -60 -60 -80 -60 -40 -120 -100 -80 -60 -40 -120 -100 -80 -60 -40 △ Day Ice CF (G16-G13), Mean △=1.64% Daytime Ice CF (G16) 3ch THM, Mean=21.73% △ Day Ice CF (G16-G13), Mean △=3.39% 100 60 60 40 80 70 20 20 60 50 40 -20 -20 30 20 -40 -60 -60 -120 -100 -80 -60 -40

LIQUID

60

40

20

-20

-40

-60

40

20

0

-20

-40

-60

-120

-100

-80

-60

-40

-120

-100

ICE



Nighttime Cloud Fraction by Phase

100

RO

70

60

50

40

30

20

-40





Nighttime Ice CF (G16) 3ch THM, Mean=31.35%







△ Night Ice CF (G16-G13), Mean △=1.93%



ICE



GOES-13/GOES-16 Consistency vs CALIOP

December 2017







day, full-disk

Ed5 more consistent than Ed4; Ed5 cloud mask not yet tuned for accuracy



Tau

Day

Optical depth and height for samples with $\Delta CF < 2\%$



-80

-80

-60

-40

-60

-40

0.8

0.6

0.4

0.2

0

-0.2

-0.4

-0.6

-0.8

Mean GOES-16 (3ch) G16 – G13 (Ed4) G16 – G13 (Ed5) Daytime tau (G16), 3ch THM Mean=9.34 △ Daytime tau (G16-G13), Mean △=-1.28 Δ Daytime tau (G16-G13), Mean Δ =0.89 60 30 60 40 25 40 40 20 20 20 20 0 15 0 -20 -20 10 -20 -40 -40 -40 -60 🞑 -120 -60 -100 -60 -120 -100 -80 -60 -40 -100 -80 -60 -120 -40 Δ Total Height (G16-G13), Mean Δ =0.21 km Δ Total Height (G16-G13), Mean Δ =0.1 km Total Height (G16) 3ch THM, Mean=4.48 km 0.8 40 10 0.6 Cloud 0.4 20 20 20 Height 0.2 Day/Nite -0.2 -20 -20 0.4 0.6 -40 0.8 -60 -60 -120 -100 -100 -80 -60 -40 -120 -100 -80 -60 -40





4.5

1.5

-1.5

-3

4.5

0

Mean GOES-16 (3ch) G16 – G13 (Ed4) G16 – G13 (Ed5) Day Liq Re (G16), Mean=13.98 µm Δ Day Liq Re (G16-G13), Mean Δ =-2.28 μ m Δ Day Liq Re (G16-G13), Mean Δ =0.94 μ m 60 40 20 20 20 16 0 0 14 -20 12 -20 -20 -40 -40 -60 -60 -60 -120 -100 -80 -60 -40 -120 -100 -80 -60 -40 -120 -100 -80 -60 -40 Day Ice Re (G16), Mean=35.04 µm Δ Day Ice Re (G16-G13), Mean Δ =-7.85 μ m Δ Day Ice Re (G16-G13), Mean Δ =2.6 μ m 60 60 55 40 40 50 4.5 45 20 20 40 1.5 35 0 1.5 30 -20 -20 -3 25 4.5 20 -40 15 -7.5 -60 -60 -60 -80 -120 -100 -60 -40 -40 -120 -100 -120 -100 -80 -60 -80 -60 -40

LIQUID

ICE

Clear-Sky Reflectance Update for 2-channel Satellites

- Ed4 overhead albedo maps from ISCCP and anisotropic models inadequate for Met-5, Met-7, and GMS-5
- Land: monthly hourly composites created for Ed5 using two years of data
- Marked improvement compared to the Ed4 method



Clear-Sky Reflectance Update for 2-channel Satellites

- Ed4 OA maps w/ fixed ocean value and VIRS bidirectional model inadequate for Met-5, Met-7, and GMS-5
- Ocean: Jin theoretical ocean reflectance model updated for SRF's for the 2-ch satellies
- Marked improvement compared to the Ed4 method









- The continuity algorithms for Ed5 clouds are progressing well.
- Revised satellite specific atmospheric correction procedures, more accurate clear-sky radiance procedures, updated cloud models, improved ancillary datasets, and cloud mask updates that better account for temporal and regional variations in WV absorption are leading to more consistent cloud properties from MODIS and VIIRS and also among GEOsats than previously achieved (demonstrated over ocean).
- Some next steps include
 - Further refinements to the ocean cloud mask
 - Incorporating a neural net applied to GEOS-IT data to better define LST's to support cloud mask refinements over land
 - Incorporating a neural net applied to GEOS-IT data to better detect clouds during polar night.
 - Implementing and testing new cloud top height and phase methods
 - Tuning for accuracy using CALIPSO and other data



New SatCORPS Capabilities



The Satellite ClOud and Radiative Property retrieval System

- The SatCORPS is an activity that has evolved synergistically with CERES.
- CERES cloud algorithms adapted to operate with low-latency to produce datasets for weather community (e.g. NCEP) and to support NASA field campaigns.
- Produce historical and long-term datasets to support needs from other agencies (e.g. DOE ARM program).
- Useful testbed for validating cloud algorithm features used in CERES.
- Processing framework, website (https://satcorps.larc.nasa.gov/indexV2.html), data dissemination and visualization services are in the process of being significantly upgraded.
- Several new capabilities recently installed.







Global Cloud Composites (GCC) from Satellites

Objective: Optimally combines radiances and derived products (cloud properties and radiative fluxes) from multiple GEO and LEO satellite imagers as seamlessly as possible

Based on system developed for DSCOVR ERB project (Khlopenkov et al., 2017, SPIE)

 Daytime only, 5-km grid, 1-2 hourly, limited set of radiances and basic cloud parameters

New system is intended for the broader community

- Partially funded by NASA SNWG to produce a multi-year, hourly dataset to serve modeling needs related to cloud parameterizations
- Day & Night, 3-km grid, 30-60 minutes
- Incorporates many CERES Ed5 cloud algorithm enhancements to improve accuracies, cross-platform consistency, and reduce artifacts (e.g sunglint, terminator)

System runs operationally to support various low latency (e.g. FlashFlux?) and NRT applications³²





10 20 30 40 50 60 70 100 Cloud Optical Depth

Global Cloud Composites (GCC) from Satellites

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Enhancing the SatCORPS with Satellite Sounding Capabilities

SatCORPS collaboration with William Smith Sr., Qi Zhang (UW) & Anthony DiNorscia (SSAI)

Creating next-gen high-res (2km /30min) GEO/LEO "hyperspectral" sounding proxy data via the fusion of current polar and geostationary satellite measurements



Data System Characteristics

- Full Spectral Resolution Used
- Full Spatial Resolution Used
- Polar Hyperspectral clear soundings above cloud & MW soundings below cloud are retrieved with 2-km spatial and 30-minute temporal resolution
- Soundings assimilated into 3-km Res. NWP (HRRR) Model
- Continuous Humidity data assimilation used to diagnose winds and dynamics
- 0-to-12-hour forecast cycle conducted every hour







SAT+RAP 200 hPa RH (Percent)



SAT-RAP 200 hPa RH (Percent)

Standard Deviations Between Radiosondes and 6-hr Forecasts (Feb/Mar 2021)



- Satellite sounding fusion data dramatically improve • definition/predicton of atmospheric thermodynamics and winds
- **CERES CWG plans to explore these high-resolution** • data for understanding/correcting RH biases in reanalyses to improve clear sky radiance simulations for the cloud mask.

Datasets, visualizations, validation tools:

100

50

-20

https://satcorps.larc.nasa.gov/cgi-bin/site/showdoc?mnemonic=phs https://www.ssec.wisc.edu/hufusion/





QUESTIONS ?